

# Pix2NPHM: Learning to Regress NPHM Reconstructions From a Single Image

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This supplementary material contains additional information about our inference-time optimization routine (Sec. 1), and, finally, we present additional qualitative result comparisons and ablations in Sec. 2.

Moreover, we highly encourage the reviewers to watch our supplementary video for improved result visualizations using rendered camera trajectories, and video tracking results.

## 1. Inference-Time Optimization

At inference-time we assume initial camera parameters to be provided, *e.g.* estimated using Pixel3DMM [3]. Additionally, we require facial segmentation masks, *e.g.* provided by FaRL [8], in order to mask out the background and occluders such as glasses, hats and hands.

Once these things have been pre-computed, we initialize our optimization procedure using our feed-forward predictions, and minimize equation 10 of the main paper. We optimize for 100 steps using  $\lambda_n = 5.0$ ,  $\lambda_p = 1.0$ ,  $\lambda_{reg} = 1.0$ ,  $\lambda_{id}^R = 0.5$  and  $\lambda_{ex}^R = 2.0$ .

## 2. Additional Results and Ablations

In the remainder of this supplementary document we provide additional qualitative result comparisons on the SVFR-NeRSemble benchmark [3] and NoW benchmark [5]. Furthermore, we include more results of our ablation experiments in Sec. 2.2.

We refer to our supplemental video for result comparisons rendered from a camera trajectory for better 3D perception.

### 2.0.1. NeRSemble [3]

For additional *posed* reconstruction comparisons against recent SotA baselines we refer to Fig. 1. Similarly, we show additional *neutral* reconstruction results in Fig. 2

### 2.1. NoW [5]

Next to the controlled reconstruction scenarios on NeRSemble, we present additional qualitative results on the in-the-

wild captures from the validation set of the NoW benchmark [5] in Fig. 3.

### 2.2. Ablations

Additional qualitative ablations results are shown in Figs. 4 and 5 for *posed* and *neutral* reconstructions on the SVFR-NeRSemble benchmark, respectively.

Fig. 6 shows ablation results on the NoW validation set.

Furthermore, we show different ablation experiments to the main paper in Fig. 7 (*posed*, NeRSemble) and Fig. 8 (*neutral*, NoW).

Additionally, Fig. 9 shows ablative comparisons on in-the-wild image from the FFHQ dataset [4].

### 2.3. In-the-Wild Results

Finally, Fig. 10 shows more in-the-wild results on FFHQ [4]. For in-the-wild tracking results we refer to our supplementary video.

## References

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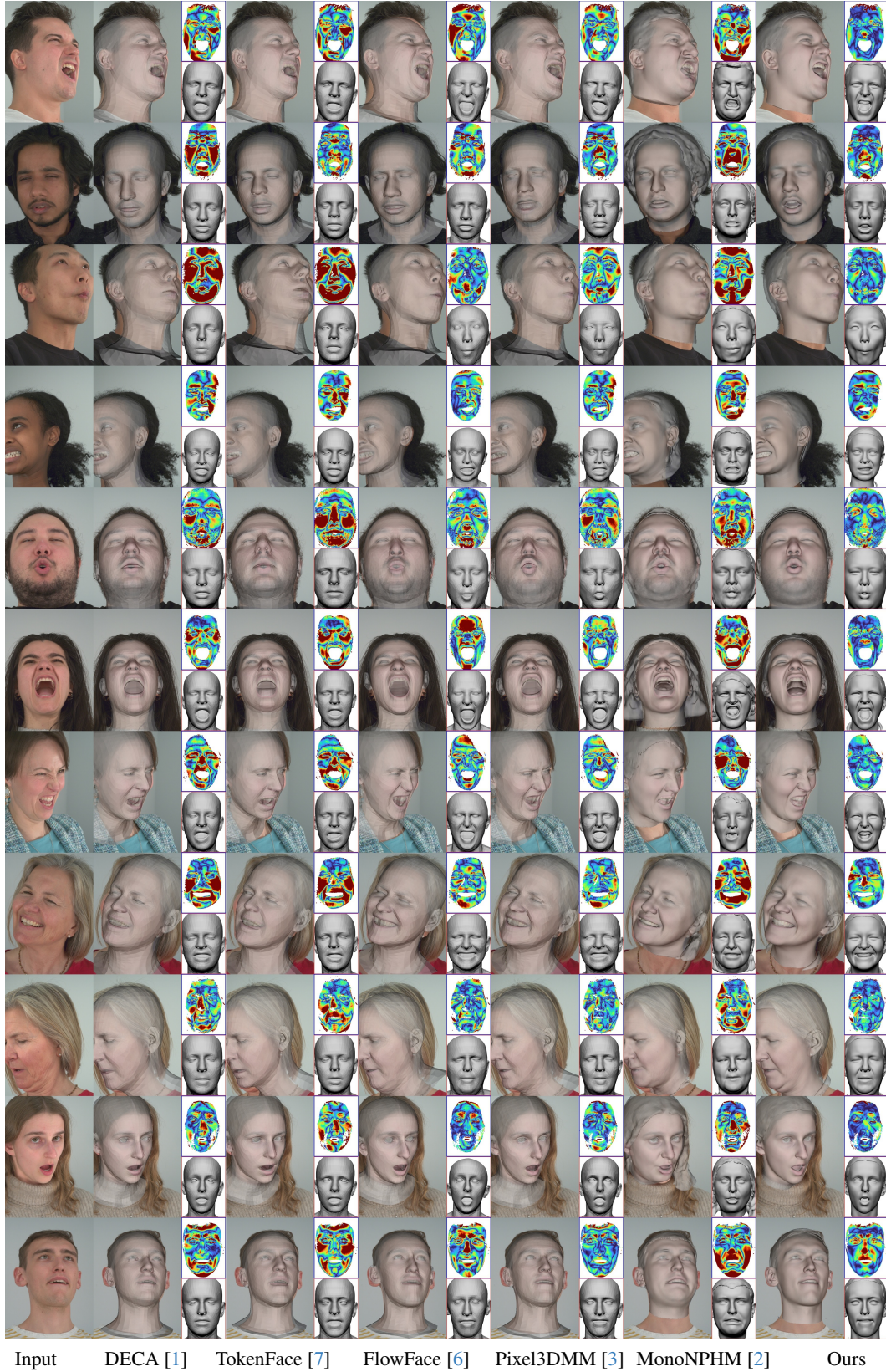


Figure 1. **Posed Reconstruction:** We show overlays of the reconstructed meshes to judge the reconstruction alignment. Insets with a blue border depict  $L_2$ -Chamfer distance as an error map, rendered from a frontal camera. Red insets show the reconstructed mesh from the same camera. All our figures are best viewed digitally and zoomed-in.



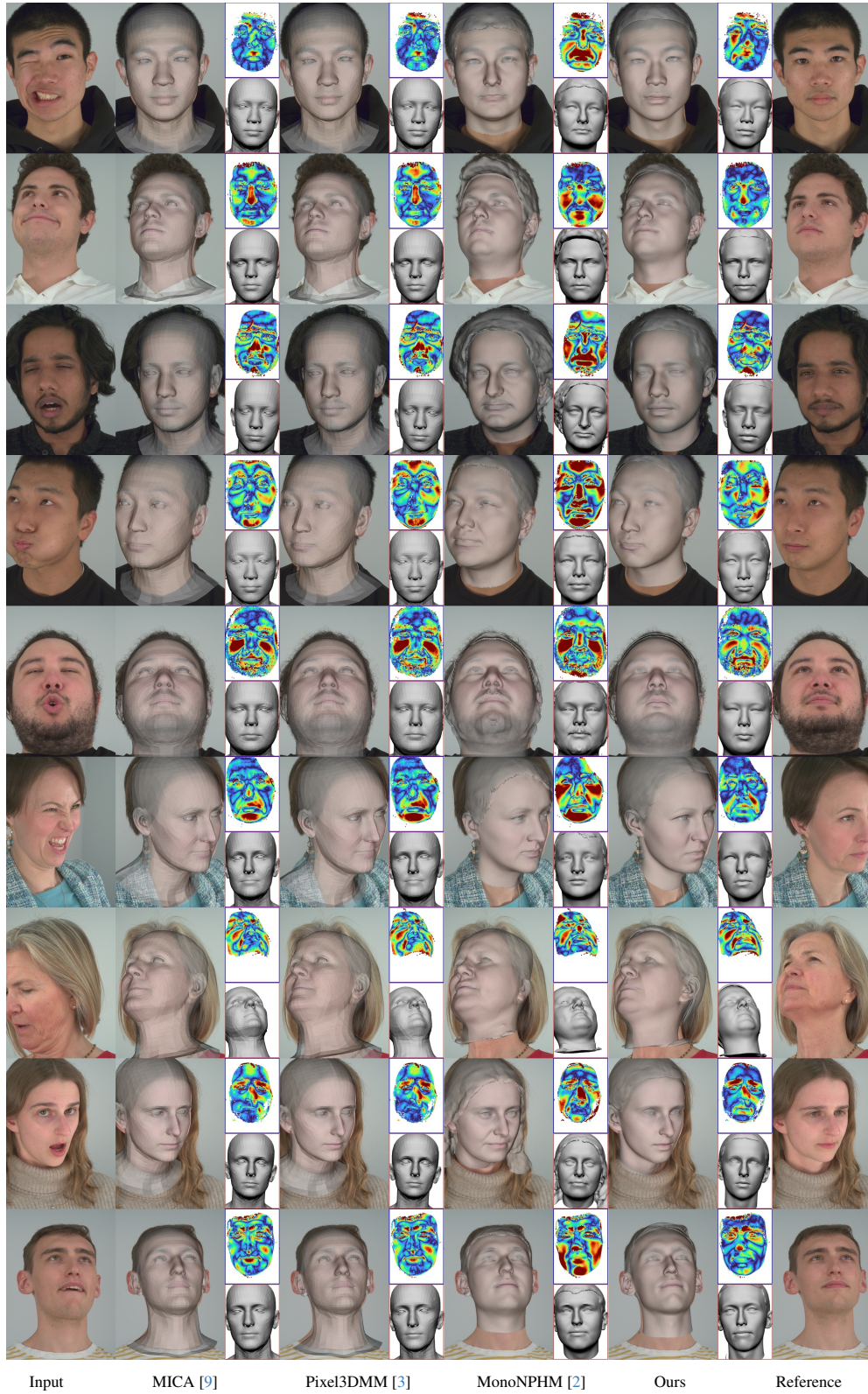


Figure 2. **Neutral Reconstruction, NeRSemble**: Comparison against available SotA methods on top of neutral reference image.



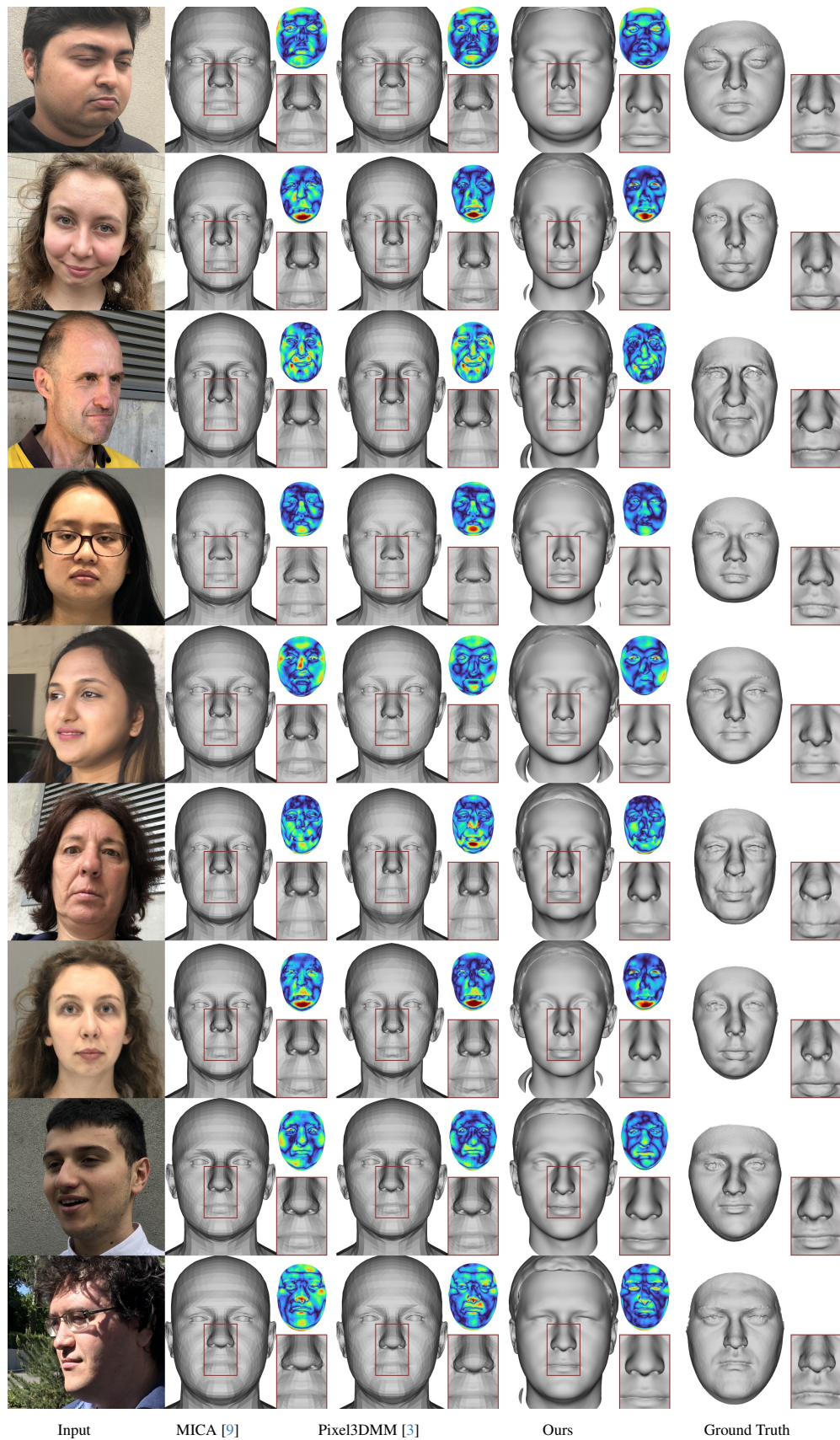


Figure 3. **Neutral Reconstruction, NoW:** We show frontal mesh renderings in comparison to the ground truth mesh, as well as, error maps and zoom ins.



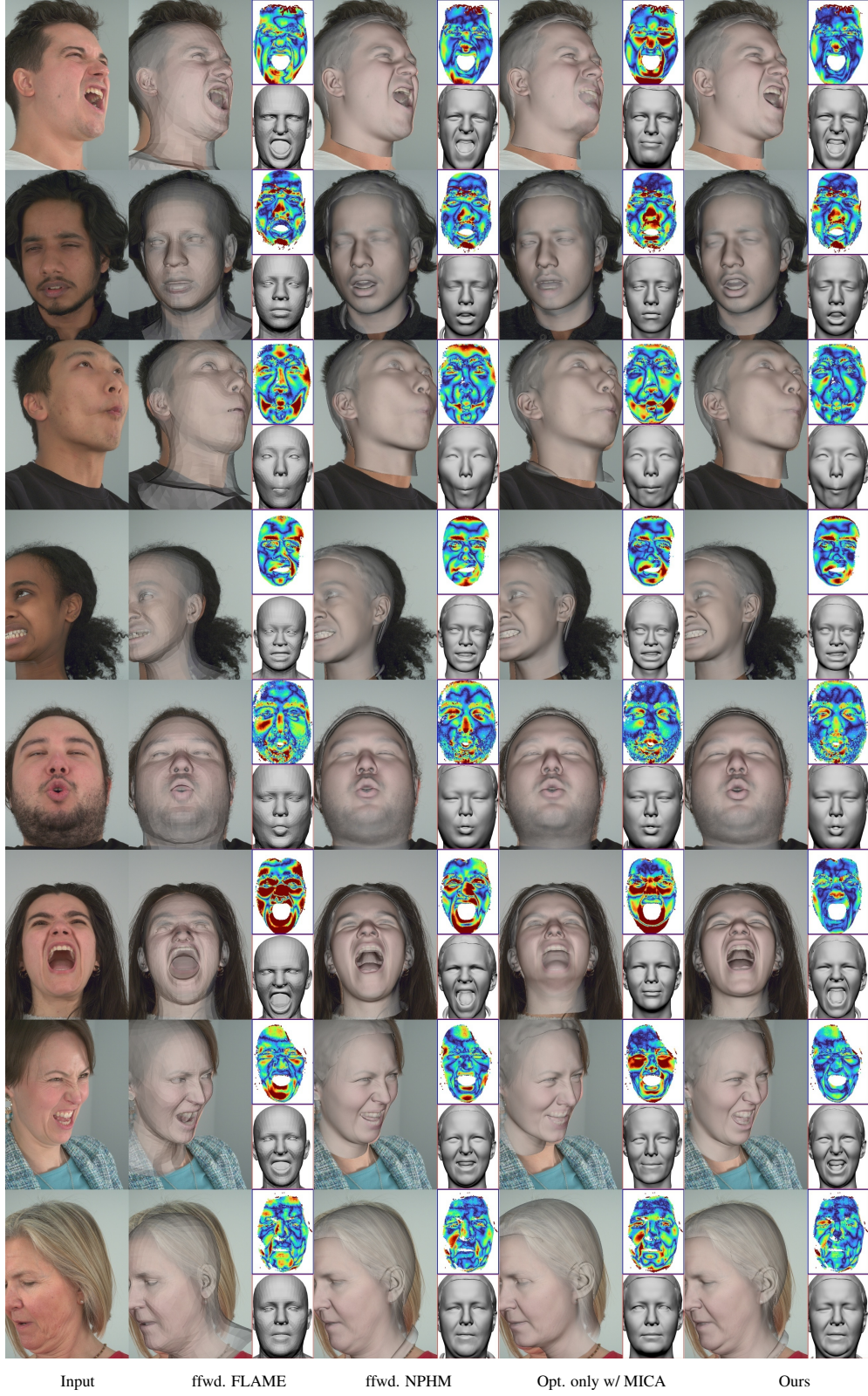


Figure 4. **Ablations, Posed:** NPHM feed-forward predictions exhibit more details compared to FLAME. Without the feed-forward initialization our optimization sometimes fails to reconstruct extreme expressions (*e.g.* see rows 1 and 3).



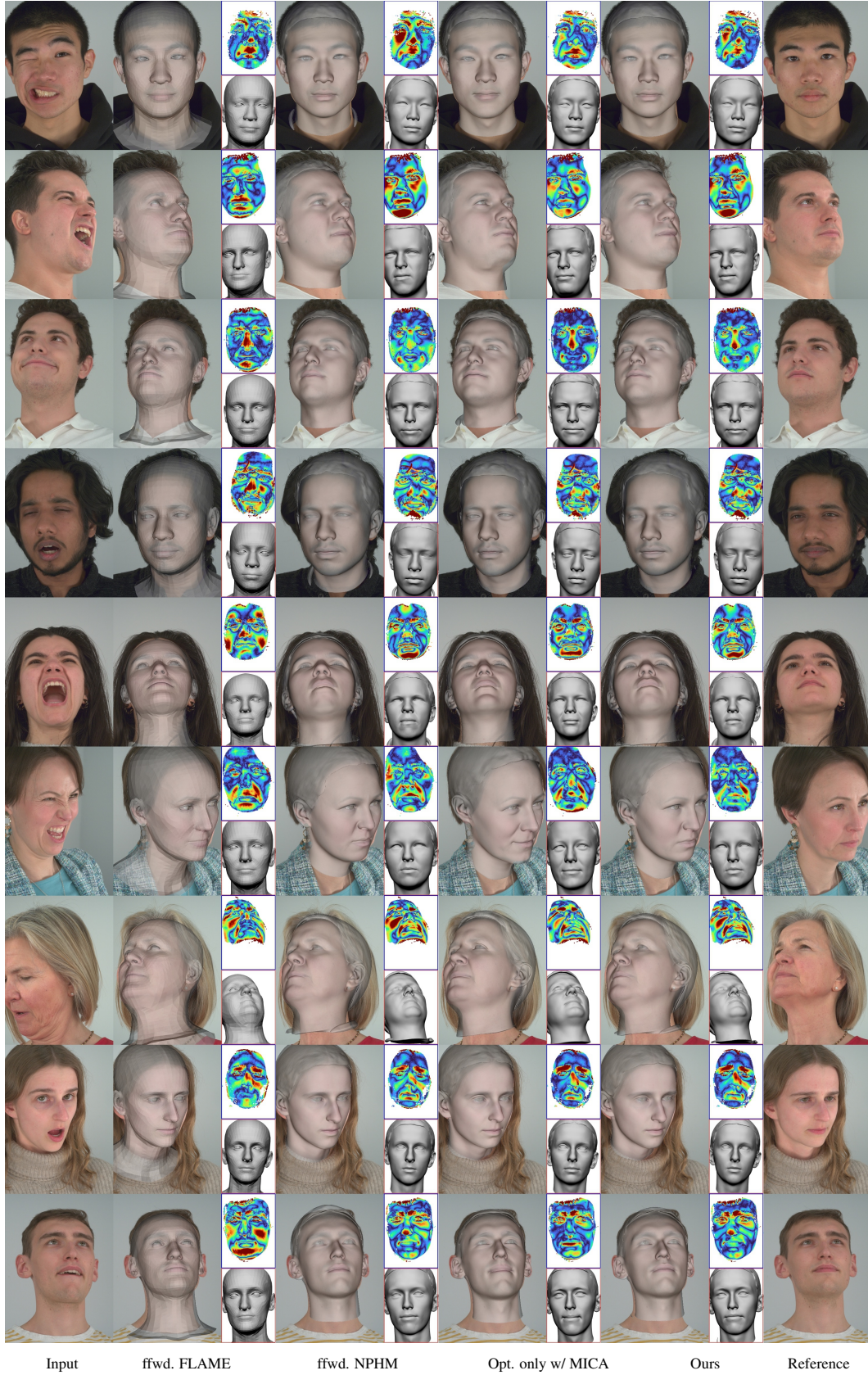


Figure 5. **Ablations, Neutral:** Without the feed-forward prior, our optimization cannot properly disentangle identity and expression.





Figure 6. Ablations, NoW.



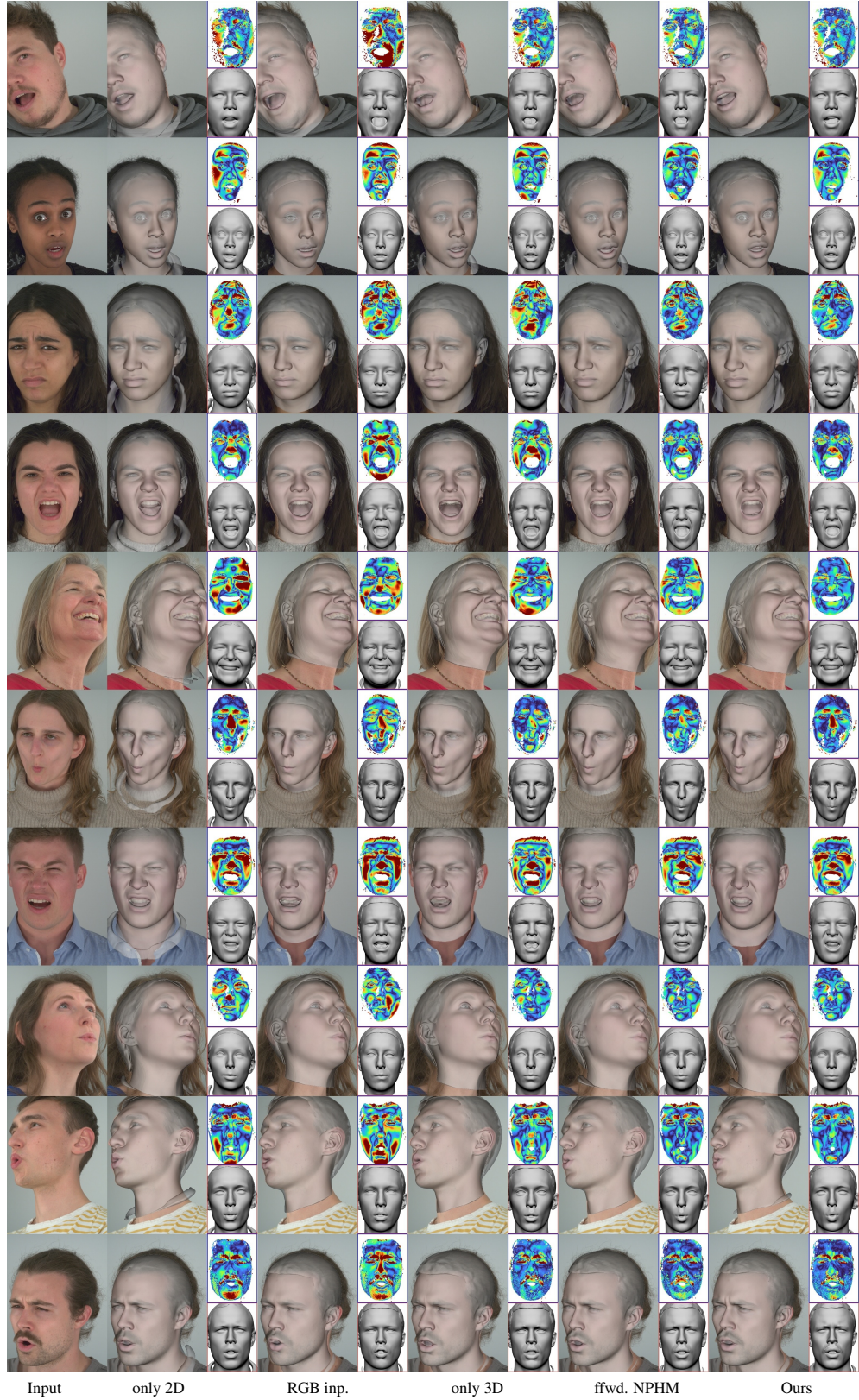


Figure 7. **Ablations, Posed:** Here we ablate different training dataset types, and different input types against our proposed feed-forward predictor and full method.



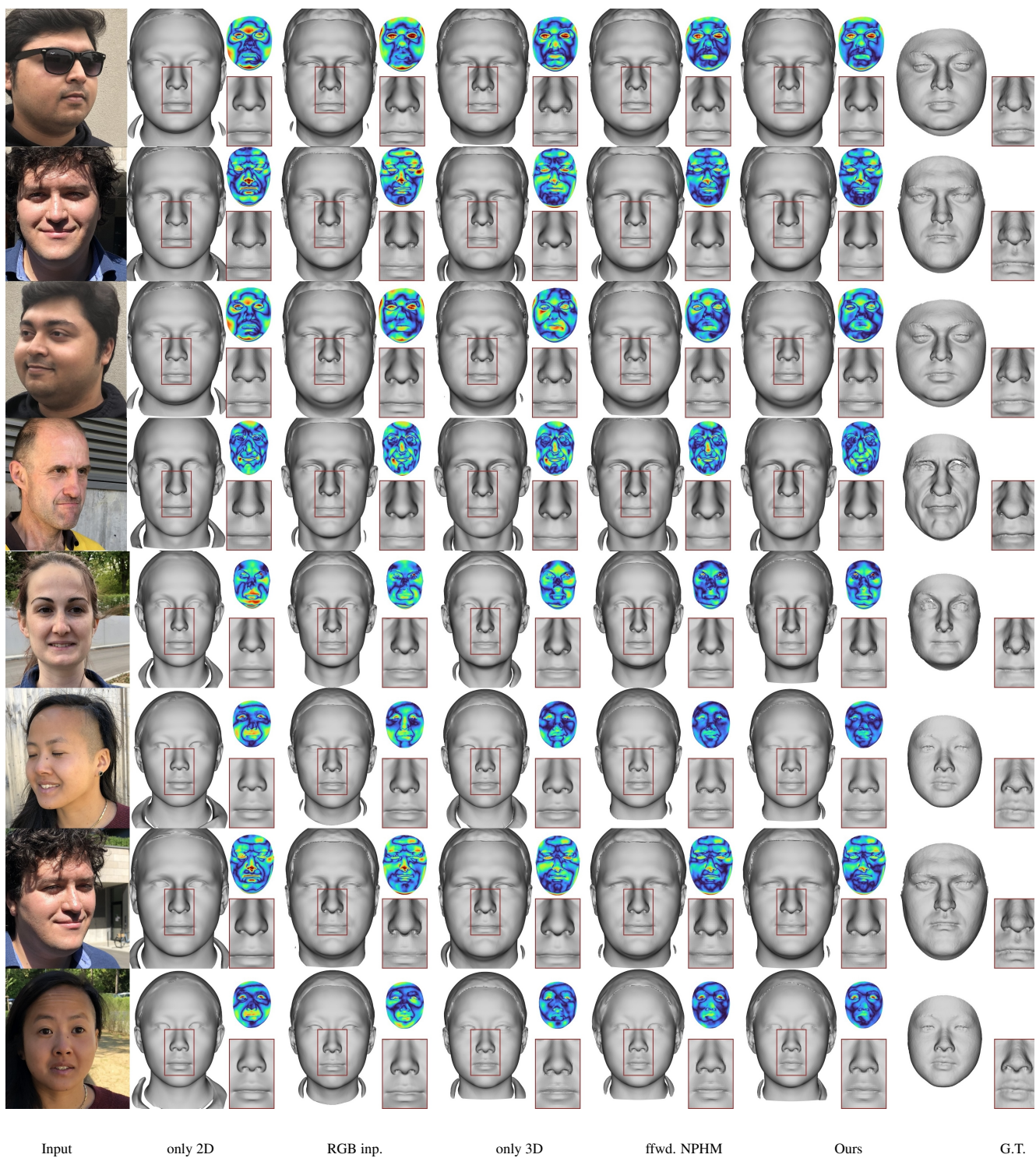


Figure 8. **Ablations, Neutral on NoW [5]:** Here we ablate different training dataset types, and different input types against our proposed feed-forward predictor and full method.





Figure 9. In-the-Wild Ablations





Figure 10. **In-the-Wild Reconstruction**